

6 axes | H62.XYZTR25S/K

Piezo Z/Tip/Tilt/Rotation Stage



Characteristics >>

- Motion in X, Y, Z, θ_x , θ_y , θ_z
- Optional closed-loop feedback sensor
- Load capacity up to 200g
- Low profile

Applications >>

- Optical beam scanning
- Light path adjustment
- Graphical stability
- Interference/metering
- Large loading tilt motion
- Space perturbation simulation system
- Calibration of acceleration sensor
- Calibration of angular velocity sensor

Introduction

H62 Piezo Hexapod is a piezo stage with 6-axis motion of θ_x , θ_y , θ_z , X, Y, and Z 6-axis movement in space is realized by the coordinated expansion and contraction of six piezoelectric actuators. The closed-loop model has high positioning accuracy. It is suited for applications such as microelectronics precision machining, test, etc.



Harbin Core Tomorrow Science & Technology Co., Ltd.

Tel: +86-451-86268790

Email: info@coremorrow.com

Headquarters: Building I2, No.191 Xuefu Road, Nangang District, Harbin

Fax: +86-451-86267847

Web: www.coremorrow.com

Shanghai Office: Building 2, No.608 Shengxia Road, Pudong District, Shanghai

Technical Data >>

Type	S-Closed loop K-Open loop	H62.XYZTR25S	H62.XYZTR25K	Units
Active axes		X, Y, Z, θ_x , θ_y , θ_z	X, Y, Z, θ_x , θ_y , θ_z	
Driving channels		7	7	
XYZ travel range (0~120V)		XY: ± 80 , Z: 160	XY: ± 80 , Z: 160	$\mu\text{m} \pm 20\%$
XYZ travel range (0~150V)		XY: ± 100 , Z: 200	XY: ± 100 , Z: 200	$\mu\text{m} \pm 20\%$
$\theta_x \theta_y \theta_z$ deflection angle (0~120V)		$\theta_x \theta_y$: ± 10 , θ_z : 1.28	$\theta_x \theta_y$: ± 10 , θ_z : 1.28	$\text{mrad} \pm 20\%$
$\theta_x \theta_y \theta_z$ deflection angle (0~150V)		$\theta_x \theta_y$: ± 12.5 , θ_z : 1.6	$\theta_x \theta_y$: ± 12.5 , θ_z : 1.6	$\text{mrad} \pm 20\%$
Integrated sensor		SGS	-	
Closed/open loop XYZ resolution		7	2	nm
Closed/open loop $\theta_x \theta_y \theta_z$ resolution		$\theta_x \theta_y$: 0.9, θ_z : 0.06	$\theta_x \theta_y$: 0.25, θ_z : 0.01	μrad
Closed-loop linearity		0.5	-	%F.S.
Closed-loop repeatability		0.2	-	%F.S.
Unloaded resonant frequency		X140/Y150/Z200 $\theta_x 270/\theta_y 280/\theta_z 110$	X140/Y150/Z200 $\theta_x 270/\theta_y 280/\theta_z 110$	Hz $\pm 20\%$
Load capacity		0.2	0.2	kg $\pm 5\%$
El. capacitance		XY $\theta_x \theta_y$: 14.4 Z: 28.8 θ_z : 3.6	XY $\theta_x \theta_y$: 14.4 Z: 28.8 θ_z : 3.6	$\mu\text{F}/\text{axis} \pm 20\%$
Material		Steel, Aluminum	Steel, Aluminum	
Operating temperature ^[1]		-20~80	-20~80	$^{\circ}\text{C}$
Mass		960(Not include cable)	960(Not include cable)	g $\pm 5\%$
Cable length ^[2]		1.5	1.5	m $\pm 10\text{mm}$
Sensor/voltage connector ^[2]		-	-	

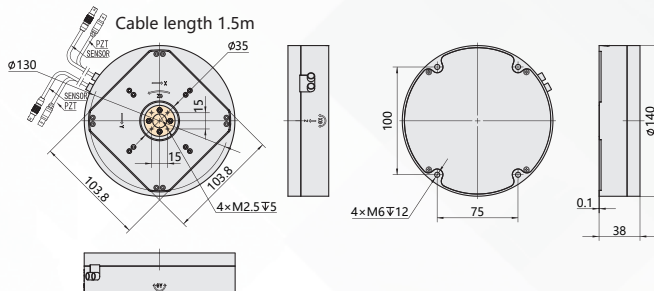
Note: Technical data are measured by CoreMorrow E00/E01 series piezo controller. Max driving voltage could be -20V~150V, 0~120V is recommended for long-term and high-reliable operation. Unless otherwise specified, the above parameters are measured at room temperature about 25 $^{\circ}\text{C}$.

[1] Custom ultralow temperature and ultrahigh vacuum versions are available.

[2] Custom cable length and connector is available.

Note: The parallelism of the moving platform is about 20 μm , and the roughness is about 1.6 to 3.2. Please contact the sales engineer for confirmation before purchase.

Drawing >>



Recommended Controllers >>



E51.D7S
 7 channels, output voltage 0~120V
 Driving 6-axis motion piezo stage
 Software control



E01.A9
 1~9 channels, Open loop
 Analog input/ Software control
 Ave current 291mA



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