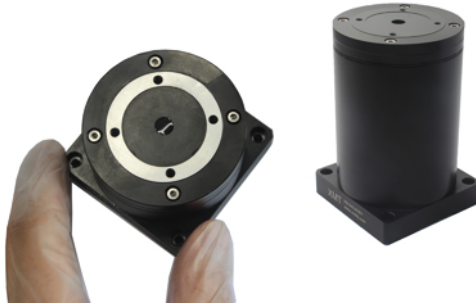


## P34 Piezo Tip/Tilt Platform

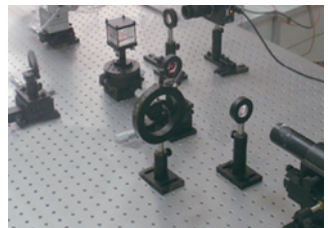
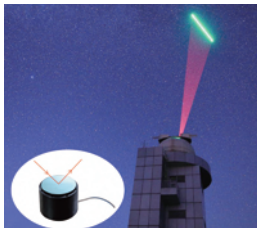
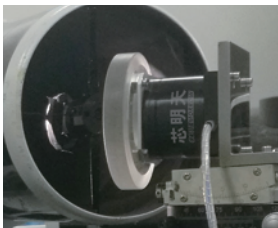
### User Manual

Version: V1.0



This document describes the following products:

- P34.T1S/K
- P34.T2S/K
- P34.T4S/K



# DECLARATION

This user manual is applicable to P34 piezo tip/tilt platform, for your smooth and correct use of this product, please read this manual carefully before using it. Please follow the instructions in the installation and use process. Improper operation may cause injury to the operator and/or damage to the product, so it is required that the entire installation and operation process should be completed by professionals with a certain foundation and a certain understanding of product principles, or under the guidance of a professional.

If you disassemble or transform the product without permission, our company will not be responsible for any consequences arising therefrom.

To change the product model and other false sales of our company's products are illegal, users should be vigilant. Once found, you should actively report or contact our company, jointly crack down on illegal acts, and prevent fraud and economic losses. CoreMorrow will investigate for the legal responsibility of the illegal subject and related party.

With the continuous development and innovation of technology, CoreMorrow will timely add the latest information to the manual as required. If you need, please contact us, or to our website [www.coremorrow.com](http://www.coremorrow.com) for download, we apologize for any inconvenience caused to you.

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## 1. Introduction >>

### 1.1 Purpose and content

- ▶ This manual is mainly for your smooth and correct use of P34 Piezo Tip/Tilt Platform
- ▶ The manual contains all the necessary information for P34 Piezo Tip/Tilt Platform.
- ▶ Introduction of the precautions during installation and use

### 1.2 Symbol and meaning



**DANGER:** Improper handling may could cause injury to the operator.



**Attention:** Improper handling can cause damage to the equipment.

- ▶ No order between items.

1. Please operating in order.
- 2.

### 1.3 Users of This Manual

The default user of this manual has knowledge of piezoelectric products and controllers, and has a certain basis for their installation and use.

### 1.4 Manual Lost and Reissued

If this manual is lost, please contact CoreMorrow. We will send you the latest version of the user manual.

## 2. Safety Guide

P34 Piezo Tip/Tilt Platform is designed with the most advanced technology and safety standards for your own safety and the correct use of the product, please observe the following points when in use.



A change in temperature and pressure will charge the piezoelectric actuator, and the actuator will remain charged for a period of time when it is disconnected from the controller, so the operator should pay attention to when in use.

- ▶ Do not disassemble P34 Piezo Tip/Tilt Platform.
- ▶ Discharge P34 before mounting, which can be done by connecting to the controller.
- ▶ Do not unplug the wire connecting with controller during operation.
- ▶ Before use, check whether the connection wire of the product is in good condition and whether the product and the controller are effectively grounded. During operation, strictly standardize the operation. Do not touch the product (up to 150V voltage) with your hand when power on, in case of danger.



In order to prevent damage to the product caused by improper operation, the following points should be paid attention to the following points when in use.

- ▶ P34 Piezo Tip/Tilt Platform should be used in a dust-free, oil-free and lubricant-free environment.
- ▶ As the product is designed with flexible structure, it is recommended that the load should not exceed load capacity of product. When loading, DO NOT apply torque force and DO NOT pry or twist the load surface, so as not to damage the structure.
- ▶ Recommended voltage range is 0~120V for long-term use and lifetime.
- ▶ Do not disassemble the product to avoid damage.
- ▶ Avoid stretching and bending the cable interface to prevent damage to the cable.
- ▶ Use the dedicated cable provided by CoreMorrow to connect P34 Piezo Tip/Tilt Platform to controller.
- ▶ Do not connect via an extension cable casually, if you need a longer cable, please contact CoreMorrow.

## 3. Product Overview

### 3.1 Product Introduction

P34 Piezo Tip/Tilt Platform has the following advantages:

▶ High performance piezo stack:

P34 piezo tip/tilt platform is driven by a highly reliable ceramic actuator with a fully insulated structure, so its performance and service life are far better than the traditional actuator. The insulating layer can effectively prevent the piezoelectric ceramic from being damaged when exposed to moisture. Therefore, the stability of piezoelectric ceramics can be guaranteed under extreme circumstances. Compared with traditional driving mechanism, there are no transmission parts and friction. Therefore, ceramic actuator has the characteristics of no rebound, maintenance free, and wear free, etc.

▶ Flexible hinge structure:

P34 Piezo Tip/Tilt Platform adopting flexible hinge mechanism has advantages of no friction, high positioning accuracy. Flexible hinge is an element not affected by static and dynamic friction, based on the elastic deformation of metal material (e.g., steel), there is no rolling and sliding parts. Flexible unit has very high load capacity and stiffness. Hinge guide needs no maintenance and no wear and tear. Suitable for a wide range of temperatures, no lubricating oil is required.

▶ Strain sensor

Strain sensor detects the position information by its own expansion. They are fixed in the proper position of the transmission part and measure the displacement of the moving part. This type of position measurement is made by contact and indirect measurement. So the displacement of the moving platform is measured by measuring lever, guide hinge, or piezoelectric ceramic stack.

P34 piezo tip/tilt platform has a travel range in  $\theta_x$   $\theta_y$  of up to 6mrad, and features fast response speed, high repeatable positioning accuracy, high flexibility, easy to operate, so it can meet different applications. This product can also be customized according to the needs.

### 3.2 Principle

The piezo control principle is as follows:

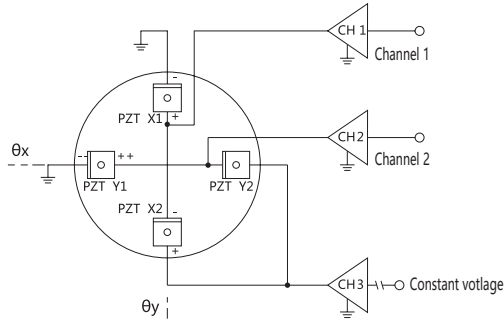


FIG. 1 P34 control principle

Piezo Tip/Tilt Platform(two-axis motion) is based on parallel kinematic design with coplanar axis and moving platform. Four piezo actuators are placed at a  $90^\circ$  angle interval, paired differential control distribution. Two pairs of differentially driven actuators provide the highest achievable angular stability over a wide temperature range. Its tilt motion is achieved by two pairs of piezo actuators in a push-pull motion, controlled by a bridge connection circuit.

The deflection angle of P34 Tip/Tilt Platform can be calculated as follows:

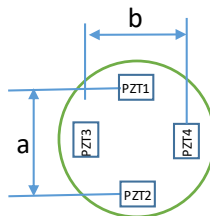


FIG. 2 Tip/Tilt Platform schematic

The deflection angle in  $\theta_x$ :

$$\theta_x = (L_{PZT1} - L_{PZT2}) / a$$

Wherein:

$L_{PZT1}$  - PZT1 Displacement;

$L_{PZT2}$  - PZT2 Displacement;

a - The distance between two piezo actuator.

Similarly, the deflection angle in  $\theta_y$ :

$$\theta_y = (L_{PZT3} - L_{PZT4}) / b$$

Dynamic characteristics of P34 Tip/Tilt Platform:

Operating frequency of P34 depends on its resonant frequency. In order to estimate its resonant frequency after loading mirror (moving surface and mirror), the moment of inertia of mirror must be taken into account. The moment of inertia of mirror is calculated as follows:

the moment of inertia of a cylindrical mirror

$$I_m = m \left[ \frac{3R^2 + H^2}{12} + \left( \frac{H}{2} + T \right)^2 \right]$$

The moment of inertia of a rectangular mirror:

$$I_m = m \left[ \frac{L^2 + H^2}{12} + \left( \frac{H}{2} + T \right)^2 \right]$$

Wherein:

$M$  - Quality of mirror

$I_m$  - The moment of inertia of mirror

$L$  - Length of the mirror perpendicular to the rotation axis



$H$  - Thickness of mirror

$T$  - Distance between the axis of rotation and the surface of the platform

$R$  - Radius of mirror

The resonant frequency of after loading mirror can be calculated by using unloaded resonant frequency and the moment of inertia of mirror. The calculation formula is as follows:

$$f' = \frac{f^0}{\sqrt{1 + I_m / I_0}}$$

Wherein:

$f'$  - Resonant frequency after loading mirror

$I^0$  - The moment of inertia of unloaded moving surface

$f$  - Unloaded operating Frequency

$I_m$  - The moment of inertia of mirror

### 3.3 Product Features

- ▶ Deflection Angle to 6mrad
- ▶ High precision sensor, high positioning accuracy
- ▶ Sub- $\mu$ rad resolution
- ▶ Fast response

### 3.4 Motion Direction

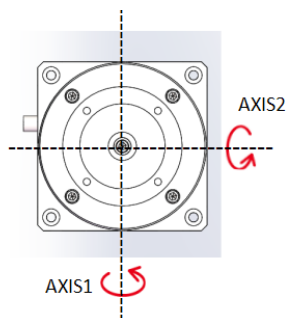


FIG. 3 The Motion Direction of P34 Piezo Tip/Tilt Platform

The labels and motion direction of P34 is as follows:

| Model                               | Motion direction | Function      | Label |
|-------------------------------------|------------------|---------------|-------|
| P34.T1S/K<br>P34.T2S/K<br>P34.T4S/K | AXIS1            | PZT Drive     | CH1   |
|                                     |                  | Senser output | 1     |
|                                     | AXIS2            | PZT Drive     | CH2   |
|                                     |                  | Senser output | 2     |
|                                     | Constant voltage | PZT Drive     | CH3   |

Table1.P34 Wire Identification and Motion Direction

## 4. Operating environment

- ▶ Operating temperature: -20~80°C
- ▶ Environment free of dust, clean, and non-corrosive substances
- ▶ Relative humidity: <60%
- ▶ Recommended voltage between 0 and 120V for long-term and high-reliability operation.

## 5. Installation and operation

Safety check should be carried out before installation, such as whether the connection wire is damaged or broken, whether the drive power supply is grounded, etc.

### 5.1 Installation and Precautions

Installation diagram of P34 is as follows:

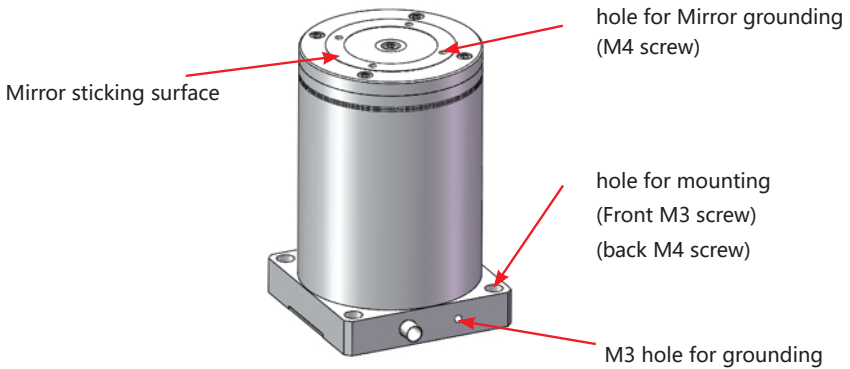


FIG. 4 P34 Installation diagram

1. Before attach the mirror, please clean the mirror and motion surface. After the mirror is glued, please wait for a period of time until adhesive solidify. And you can use a mirror adapter, as shown below.



FIG. 5 mirror adhesive and mirror adapter

2. You need to use M3 screws to mount the P34, and you also can adopt a adapter, and we have many adapters for your choice, as shown below. And before mount, please clean the mounting surface and adapter.

3. Mount P34 on the mounting surface directly or by a adapter. Please contact us, if you don't mount it with stand, such as lean or lateral mounting.



FIG. 6 Transfer adapter

4. Grounding protection for connection, as shown in Figure 7:

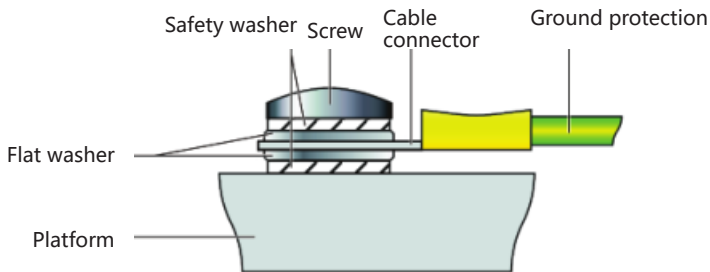


FIG. 7 Grounding protection diagram

5. Connect the P34 connector with the controller.

**Mounting notes:**

- ▶ Do not knock the moving part of the product to prevent flexure hinge deformation affecting the movement accuracy, or even damage the product.
- ▶ Do not drop the mirror adhesive into the gap at the moving end, and do not have other objects to hinder the movement, so as not to affect the accuracy or damage the equipment.

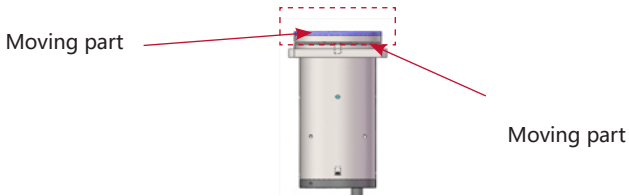


FIG. 8 Flexure hinge diagram

- ▶ Please select appropriate screw for the mounting connection, to prevent the mounting is not firm and mirror falls off, causing permanent damage. Please pay attention to standard operation during the whole mounting and operation process. Users should carry out relevant operation under the guidance of professionals.

## 5.2 Load

When mounting the load, ensure that the load quality is less than the maximum load capacity of P34, and try to mount the load in the center of the moving surface.

The correct position to mount the load is shown below:

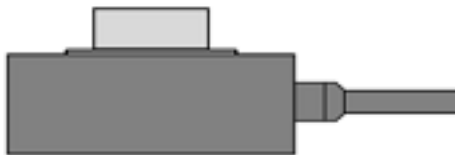


FIG.9 The load is applied to the center of the moving surface

For the protection of the product, we do not recommend that the load is too high. If a high load must be used, please appropriately low the position of the center of gravity of the load. The wrong mounting way is shown in the figure below.

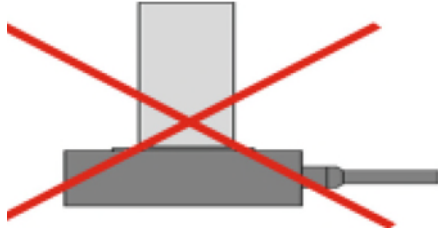


FIG.10 Try not to let the position of the center of gravity far exceed the active platform

It is forbidden to mount the load on one side of the moving platform, which will cause serious damage to the product, as shown in the figure below.

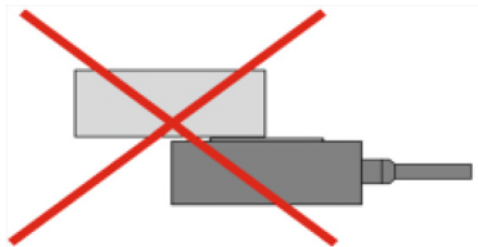


FIG.11 Do not mount long loads on one side of the platform

**Notice:**

- ▶ When installing the load, tighten the load slowly. The torque should not be too large to prevent damage to the mechanism.
- ▶ Avoid stretching and bending cables;
- ▶ Use the dedicated cable provided by CoreMorrow to connect P34 and the controller.
- ▶ Do not connect via an extension cable casually, if you need a longer cable, please contact CoreMorrow.

## 5.3 Operating

Please reconfirm the following information before turning on the power:

- ▶ P34 piezo tip/tilt platform has been grounded protection;
- ▶ The operating environment meets the operating environment requirements of P34.
- ▶ Fixed screws must be tightened.

After the above information is confirmed, relevant controller operations can be carried out:

1. Please read the user manual of the controller carefully before operation, and then start the controller.

2. Set the controller' output voltage to zero first.

3. Check no abnormal phenomenon, then input voltage value (via keyboard or analog control) according to specified input voltage range.

4. Operating normally within the rated voltage range of piezoelectric ceramics (0~120V, maximum 150V).

5. After use, please carry out voltage reset operation.

Please take light steps when P34 in operation, do not knock the product, so as not to affect the use of the product or even damage the product.

In order to achieve better motion precision of P34, it is recommended to use our company's supporting controller. Please refer to the user manual of the controller for the specific operation to ensure correct operation before relevant operation.

### **Notice:**

- ▶ The driving voltage shall not exceed the voltage range of P34.
- ▶ If any abnormal noise or oscillation occurs during use, turn off the power immediately and check the parameter setting.

## 6. Transportation and inspection

### 6.1 Transportation

This product is packed in cartons. Transportation is carried out under the packaging conditions. This product can be transported by various means of transport under normal circumstances. In the process of transportation, direct rain and snow, corrosive substances, strong collision, extrusion, irregular placement and other improper behaviors should be avoided as far as possible.

### 6.2 Open-Box Inspection

#### **Inspection content:**

- ▶ Before opening the package, please check the outer packing carefully to see if there is any breakage, wetting, dampness, deformation, etc.
- ▶ Please check the completeness of package contents one by one according to the supply contract and packing list.
- ▶ Check whether the surface of the product has obvious damage.
- ▶ Check whether the product identification is clear and complete.
- ▶ Check whether the connector is loose and the connector wire is broken or damaged.

In case of any of the above, please make a detailed record and take a photo of it. Meanwhile, please contact us for processing immediately.

#### **Attention:**

- ▶ Please handle with care when opening the package, so as not to knock against the product and cause permanent damage to it.
- ▶ Please do not use heavy tools or rough way to open.
- ▶ Please do not discard all the packaging materials which are needed for repair and return.



## 7. Maintenance and Treatment

### 7.1 Problem Handling

FAQ are shown in the table below.

| Problem description                            | Possible reason   | Solution   |
|--|---|--|
| No displacement or less displacement           | The connection wire is not connected properly or poor contact | Check the connection wire                          |
|  | Excessive load  | Load according to the product' s load capacity     |
|  | Sensor zero drift   | Check the sensor                                   |
| Low accuracy                                   | Mountingsurface unevenness                                    | Mount the platform on a flat surface               |
|  | Loose connection  | Fasten connection                                  |
|  | Wrong connection  | Check if the wiring is correct                     |
| Vibration or inaccurate positioning at startup | Incorrect input control parameters                            | Stop immediately and check the parameter Settings  |
|  | Resonance occurs  | Make drive frequency less than resonance frequency |

Table 2 FAQ and solutions

If the user cannot solve the problem by himself in the process of using, please record the problem in detail and contact CoreMorrow, and professional technical personnel will help to solve.

Problems caused by improper operation are not covered by the warranty.

CoreMorrow is not responsible for any problems caused by dismantling products without permission.

## 7.2 Daily maintenance

If the product is not used for a long time, please store it in a dust-free, well-ventilated, clean and non-corrosive indoor environment after packaging.

In the daily maintenance, please do not loosen the bolts on the product structure, so as not to affect the movement accuracy of the product.

### **Daily cleaning:**

Please disconnect the product from the controller before cleaning the surface of the product.

When cleaning, gently wipe the surface of the product with a towel dipped in a small amount of detergent, and then clean it with alcohol. Please do not use ultrasonic cleaner.

When cleaning the surface, try not to pick up the product. If you have to pick up the product, it is better to put the sponge under the product for protection. The product should not be too high from the sponge, in case the product falls off.

## 7.3 Disposal

Waste products should be disposed according to national and local rules and regulations. In order to fulfill our responsibility as a product manufacturer, we will dispose all old equipments on the market in an environmentally friendly manner. If you have equipment that cannot be disposed, you can ship it to CoreMorrow.

Address: Building I2, No.191 Xuefu Road, Nangang District, Harbin, HLJ, China

Tel: +86-451-86268790



## 8. Customer Service

If you have questions about the products you are currently using, please let us know the following information:

- ▶ Product model and relevant number
- ▶ The controller model
- ▶ Software driver version
- ▶ Computer operating system that installs supporting software

## 9. Contact us

**CoreMorrow Ltd.**

Tel: +86-451-86268790

Email: [info@coremorrow.com](mailto:info@coremorrow.com)

Website: [www.coremorrow.com](http://www.coremorrow.com)

Address: Building I2, No.191 Xuefu Road, Nangang District, Harbin, HLJ, China

**CoreMorrow Official and CTO WeChat are below:**

